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Niku offers comprehensive, yet concise coverage of robotics that will appeal to engineers. Robotic applications are drawn from a wide variety of fields. Emphasis is placed on design along with analysis and modeling. Kinematics and dynamics are covered extensively in an accessible style. Vision systems are discussed in detail, which is a cutting-edge area in robotics. Engineers will also find a running design project that reinforces the concepts by having them apply what they've learned.

Maintaining the outstanding features and practical approach that led the bestselling first edition to become a standard textbook in engineering classrooms worldwide, Clarence de Silva's Vibration: Fundamentals and Practice, Second Edition remains a solid instructional tool for modeling, analyzing, simulating, measuring, monitoring, testing, controlling, and designing for vibration in engineering systems. It condenses the author's distinguished and extensive experience into an easy-to-use, highly practical text that prepares students for real problems in a variety of engineering fields. What's New in the Second Edition? A new chapter on human response to vibration, with practical considerations Expanded and updated material on vibration monitoring and diagnosis Enhanced section on vibration control, updated with the latest techniques and methodologies New worked examples and end-of-chapter problems. Incorporates software tools, including LabVIEWTM, SIMULINK®, MATLAB®, the LabVIEW Sound and Vibration Toolbox, and the MATLAB Control Systems Toolbox Enhanced worked examples and new solutions using MATLAB and SIMULINK The new chapter on human response to vibration examines representation of vibration detection and perception by humans as well as specifications and regulatory guidelines for human vibration environments. Remaining an indispensable text for advanced undergraduate and graduate students, Vibration: Fundamentals and Practice, Second Edition builds a unique and in-depth understanding of vibration on a sound framework of practical tools and applications.

This unique textbook takes the student from the initial steps in modeling a dynamic system through development of the mathematical models needed for feedback control. The generously-illustrated, student-friendly text focuses on fundamental theoretical development rather than the application of commercial software. Practical details of machine design are included to motivate the non-mathematically inclined student.

The first comprehensive and up-to-date reference on mechatronics, Robert Bishop's The Mechatronics Handbook was quickly embraced as the gold standard for the field. With updated coverage on all aspects of mechatronics, The Mechatronics Handbook, Second Edition is now available as a two-volume set. Each installment offers focused coverage of a particular area of mechatronics, supplying a convenient and flexible source of specific information. This seminal

work is still the most exhaustive, state-of-the-art treatment of the field available. Mechatronics Systems, Sensors, and Actuators: Fundamentals and Modeling presents an overview of mechatronics, providing a foundation for those new to the field and authoritative support for seasoned professionals. The book introduces basic definitions and the key elements and includes detailed descriptions of the mathematical models of the mechanical, electrical, and fluid subsystems that comprise mechatronic systems. New chapters include Mechantronics Engineering Curriculum Design and Numerical Simulation. Discussion of the fundamental physical relationships and mathematical models associated with commonly used sensor and actuator technologies complete the coverage. Features Introduces the key elements of mechatronics and discusses new directions Presents the underlying mechanical and electronic mathematical models comprising many mechatronic systems Provides a detailed discussion of the process of physical system modeling Covers time, frequency, and sensor and actuator characteristics

"Piezoelectric-Based Vibration-control Systems: Applications in Micro/Nano Sensors and Actuators" covers: Fundamental concepts in smart (active) materials including piezoelectric and piezoceramics, magnetostrictive, shape-memory materials, and electro/magneto-rheological fluids; Physical principles and constitutive models of piezoelectric materials; Piezoelectric sensors and actuators; Fundamental concepts in mechanical vibration analysis and control with emphasis on distributed-parameters and vibration-control systems; and Recent advances in piezoelectric-based microelectromechanical and nanoelectromechanical systems design and implementation.

Written by a professor with extensive teaching experience, System Dynamics and Control with Bond Graph Modeling treats system dynamics from a bond graph perspective. Using an approach that combines bond graph concepts and traditional approaches, the author presents an integrated approach to system dynamics and automatic controls. The textbook guides students from the process of modeling using bond graphs, through dynamic systems analysis in the time and frequency domains, to classical and state-space controller design methods. Each chapter contains worked examples, review exercises, problems that assess students' grasp of concepts, and open-ended "challenges" that bring in real-world engineering practices. It also includes innovative vodcasts and animated examples, to motivate student learners and introduce new learning technologies. A textbook for engineers on the basic techniques in the analysis and design of automatic control systems.

System Dynamics and Control with Bond Graph ModelingCRC Press "Space Vehicle Dynamics and Control provides a solid foundation in dynamic modeling, analysis, and control of space vehicles. More than 200 figures, photographs, and tables are featured in detailed sections covering the fundamentals of controlling orbital, attitude, and structural motions of space vehicles. The textbook highlights a range of orbital maneuvering and control

problems: orbital transfer, rendezvous, and halo orbit determination and control. Rotational maneuvering and attitude control problems of space vehicles under the influence of reaction jet firings, internal energy dissipation, or momentum transfer via reaction wheels and control moment gyros are treated in detail. The textbook also highlights the analysis and design of attitude control systems in the presence of structural flexibility and/or propellant sloshing. At the end of each chapter, Dr. Wie includes a helpful list of references for graduate students and working professionals studying spacecraft dynamics and control. A bibliography of more than 350 additional references in the field of spacecraft guidance, control, and dynamics is also provided at the end of the book. This text requires a thorough knowledge of vector and matrix algebra, calculus, ordinary differential equations, engineering mechanics, and linear system dynamics and control. The first two chapters provide a summary of such necessary background material. Since some problems may require the use of software for the analysis, control design, and numerical simulation, readers should have access to computational software (i.e., MATLAB) on a personal computer.

Presenting a unified modeling approach to demonstrate the common components inherent in all physical systems, Control Strategies for Dynamic Systems comprehensively covers the theory, design, and implementation of analog, digital, and advanced control systems for electronic, aeronautical, automotive, and industrial applications. Detailing advanced tools and strategies used to analyze controller performance, the book summarizes hardware and software utilization; frequency response and root locus methods; the evaluation of PID, phase-lag, and phase-lead controllers; and the effect of disturbances and command inputs on steady-state errors. It also includes numerous case studies and MATLAB® examples.

"Integrates a broad range of physics, algorithms, and sensing techniques for development of intelligent systems. Highlights adaptive least-squared error modeling. Covers complex sampling, physical system modeling using digital filters, frequency domain processing, beamforming, and much more."

This Second Edition continues the fine tradition of its predecessor by exploring the various automatic control systems in aircraft and on board missiles. Considerably expanded and updated, it now includes new or additional material on: the effectiveness of beta-beta feedback as a method of obtaining coordination during turns using the F-15 as the aircraft model; the root locus analysis of a generic acceleration autopilot used in many air-to-air and surface-to-air guided missiles; the guidance systems of the AIM-9L Sidewinder as well as bank-to-turn missiles; various types of guidance, including proportional navigation and line-of-sight and lead-angle command guidance; the coupling of the output of a director fire control system into the autopilot; the analysis of multivariable control systems; and methods for modeling the human pilot, plus the integration of the human pilot into an aircraft flight control system. Also features many new additions to the appendices.

The book blends readability and accessibility common to undergraduate control systems texts with the mathematical rigor necessary to form a solid theoretical foundation. Appendices cover linear algebra and provide a Matlab overiew and files. The reviewers pointed out that this is an ambitious project but one that will pay off because of the lack of good up-to-date textbooks in the area.

This textbook is ideal for a course in engineering systems dynamics and controls. The work is a comprehensive treatment of the analysis of lumped parameter physical systems. Starting with a discussion of mathematical models in general, and ordinary differential equations, the book covers input/output and state space models, computer simulation and modeling methods and techniques in mechanical, electrical, thermal and fluid domains. Frequency domain methods, transfer functions and frequency response are covered in detail. The book concludes with a treatment of stability, feedback control (PID, lead-lag, root locus) and an introduction to discrete time systems. This new edition features many new and expanded sections on such topics as: solving stiff systems, operational amplifiers, electrohydraulic servovalves, using Matlab with transfer functions, using Matlab with frequency response, Matlab tutorial and an expanded Simulink tutorial. The work has 40% more end-of-chapter exercises and 30% more examples.

MECHANICAL VIBRATIONS: THEORY AND APPLICATIONS takes an applications-based approach at teaching students to apply previously learned engineering principles while laying a foundation for engineering design. This text provides a brief review of the principles of dynamics so that terminology and notation are consistent and applies these principles to derive mathematical models of dynamic mechanical systems. The methods of application of these principles are consistent with popular Dynamics texts. Numerous pedagogical features have been included in the text in order to aid the student with comprehension and retention. These include the development of three benchmark problems which are revisited in each chapter, creating a coherent chain linking all chapters in the book. Also included are learning outcomes, summaries of key concepts including important equations and formulae, fully solved examples with an emphasis on real world examples, as well as an extensive exercise set including objective-type questions. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

This book represents an attempt to organize and unify the diverse methods of analysis of feedback control systems and presents the fundamentals explicitly and clearly. The scope of the text is such that it can be used for a two-semester course in control systems at the level of undergraduate students in any of the various branches of engineering (electrical, aeronautical, mechanical, and chemical). Emphasis is on the development of basic theory. The text is easy to follow and contains many examples to reinforce the understanding of the theory. Several software programs have been developed in MATLAB platform for better

understanding of design of control systems. Many varied problems are included at the end of each chapter. The basic principles and fundamental concepts of feedback control systems, using the conventional frequency domain and time-domain approaches, are presented in a clearly accessible form in the first portion (chapters 1 through 10). The later portion (chapters 11 through 14) provides a thorough understanding of concepts such as state space, controllability, and observability. Students are also acquainted with the techniques available for analysing discrete-data and nonlinear systems. The hallmark feature of this text is that it helps the reader gain a sound understanding of both modern and classical topics in control engineering.

This book provides a broad range of topics on fluid dynamics for advanced scientists and professional researchers. The text helps readers develop their own skills to analyze fluid dynamics phenomena encountered in professional engineering by reviewing diverse informative chapters herein.

Modeling and Analysis of Dynamic Systems, Second Edition introduces MATLAB®, Simulink®, and SimscapeTM and then uses them throughout the text to perform symbolic, graphical, numerical, and simulation tasks. Written for junior or senior level courses, the textbook meticulously covers techniques for modeling dynamic systems, methods of response analysis, and provides an introduction to vibration and control systems. These features combine to provide students with a thorough knowledge of the mathematical modeling and analysis of dynamic systems. See What's New in the Second Edition: Coverage of modeling and analysis of dynamic systems ranging from mechanical to thermal using Simscape Utilization of Simulink for linearization as well as simulation of nonlinear dynamic systems Integration of Simscape into Simulink for control system analysis and design Each topic covered includes at least one example, giving students better comprehension of the subject matter. More complex topics are accompanied by multiple, painstakingly worked-out examples. Each section of each chapter is followed by several exercises so that students can immediately apply the ideas just learned. End-of-chapter review exercises help in learning how a combination of different ideas can be used to analyze a problem. This second edition of a bestselling textbook fully integrates the MATLAB Simscape Toolbox and covers the usage of Simulink for new purposes. It gives students better insight into the involvement of actual physical components rather than their mathematical representations.

This book describes the active vibration control techniques which have been developed to suppress excessive vibrations of structures. It covers the fundamental principles of active control methods and their applications and shows how active vibration control techniques have replaced traditional passive vibration control. The book includes coverage of dynamic modeling, control design, sensing methodology, actuator mechanism and electronic circuit design, and the implementation of control algorithms via digital controllers. An in-depth approach has been taken to describe the modeling of structures for control design, the development of control algorithms suitable for structural control, and the implementation of control algorithms by means of Simulink block diagrams or C language. Details of currently available actuators and sensors and electronic circuits for signal conditioning and filtering have been provided based on the most recent advances in the field. The book is used as a textbook for students and a reference for researchers who are interested in studying cutting-edge technology. It will be a valuable resource for academic and industrial researchers and professionals involved in the design and manufacture of active vibration controllers for structures in a wide variety of fields and industries including the automotive, rail, aerospace, and civil engineering sectors.

This book gives an in-depth introduction to the areas of modeling, identification, simulation, and optimization. These scientific topics play an increasingly dominant part in many engineering areas such as electrotechnology, mechanical engineering, aerospace, and physics. This book represents a unique and concise treatment of the mutual interactions among these topics. Techniques for solving general nonlinear optimization problems as they arise in identification and many synthesis and design methods are detailed. The main points in deriving mathematical models via prior knowledge concerning the physics describing a system are emphasized. Several chapters discuss the identification of black-box models. Simulation is introduced as a numerical tool for calculating time responses of almost any mathematical model. The last chapter covers optimization, a generally applicable tool for formulating and solving many engineering problems.

Broad-based introduction to engineering systems, presenting a unified treatment of disparate physical systems.

Fuzzy modeling has become one of the most productive and successful results of fuzzy logic. Among others, it has been applied to knowledge discovery, automatic classification, long-term prediction, or medical and engineering analysis. The research developed in the topic during the last two decades has been mainly focused on exploiting the fuzzy model flexibility to obtain the highest accuracy. This approach usually sets aside the interpretability of the obtained models. However, we should remember the initial philosophy of fuzzy sets theory directed to serve the bridge between the human understanding and the machine processing. In this challenge, the ability of fuzzy models to express the behavior of the real system in a comprehensible manner acquires a great importance. This book collects the works of a group of experts in the field that advocate the interpretability improvements as a mechanism to obtain well balanced fuzzy models.

This is an introduction to the mathematical basis of finite element analysis as applied to vibrating systems. Finite element analysis is a technique that is very important in modeling the response of structures to dynamic loads. Although this book assumes no previous knowledge of finite element methods, those who do have knowledge will still find the book to be useful. It can be utilised by aeronautical, civil, mechanical, and structural engineers as well as naval architects. This second edition includes information on the many developments that have taken place over the last twenty years. Existing chapters have been expanded where necessary, and three new chapters have been included that discuss the vibration of shells and multi-layered elements and provide an introduction to the hierarchical finite element method.

With its inclusion of the fundamentals, systems and applications, this reference provides readers with the basics of micro energy conversion along with expert knowledge on system electronics and real-life microdevices. The authors address different aspects of energy harvesting at the micro scale with a focus on miniaturized and microfabricated devices. Along the way they provide an overview of the field by compiling knowledge on the design, materials development, device realization and aspects of system integration, covering emerging technologies, as well as applications in power management, energy storage, medicine and low-power system electronics. In addition, they survey the energy harvesting principles based on chemical, thermal, mechanical, as well as hybrid and nanotechnology approaches. In unparalleled detail this volume presents the complete picture -- and a peek into the future -- of micro-powered microsystems.

Annotation Consisting primarily of contributions written by engineers from Europe, Asia, and the US, this volume provides a general methodology for describing, solving, and analyzing discontinuous systems. The focus is on mechanical engineering problems where clearances, piecewise stiffness, intermittent contact, variable friction, or other forms of discontinuity occur.

Practical applications include vibration absorbers, percussive drilling of hard materials, and dynamics of metal cutting. Of likely interest to new and experienced researchers working in the field of applied mathematics and physics, mechanical and civil engineering, and manufacturing. Lacks a subject index. Annotation copyrighted by Book News, Inc., Portland, OR.

Using MATLAB® and Simulink® to perform symbolic, graphical, numerical, and simulation tasks, Modeling and Analysis of Dynamic Systems provides a thorough understanding of the mathematical modeling and analysis of dynamic systems. It meticulously covers techniques for modeling dynamic systems, methods of response analysis, and vibration and control systems. After introducing the software and essential mathematical background, the text discusses linearization and different forms of system model representation, such as state-space form and input-output equation. It then explores translational, rotational, mixed mechanical, electrical, electromechanical, pneumatic, liquid-level, and thermal systems. The authors also analyze the time and frequency domains of dynamic systems and describe free and forced vibrations of single and multiple degree-of-freedom systems, vibration suppression, modal analysis, and vibration testing. The final chapter examines aspects of control system analysis, including stability analysis, types of control, root locus analysis, Bode plot, and full-state feedback. With much of the material rigorously classroom tested, this textbook enables undergraduate students to acquire a solid comprehension of the subject. It provides at least one example of each topic, along with multiple worked-out examples for more complex topics. The text also includes many exercises in each chapter to help students learn firsthand how a combination of ideas can be used to analyze a problem.

This fourth volume of eight from the IMAC - XXXII Conference, brings together contributions to this important area of research and engineering. The collection presents early findings and case studies on fundamental and applied aspects of Structural Dynamics, including papers on: Linear Systems Substructure Modelling Adaptive Structures Experimental Techniques Analytical Methods Damage Detection Damping of Materials & Members Modal Parameter Identification Modal Testing Methods System Identification Active Control Modal Parameter Estimation Processing Modal Data

This open access book presents the findings of Collaborative Research Center Transregio 40 (TRR40), initiated in July 2008 and funded by the German Research Foundation (DFG). Gathering innovative design concepts for thrust chambers and nozzles, as well as cutting-edge methods of aft-body flow control and propulsion-component cooling, it brings together fundamental research undertaken at universities, testing carried out at the German Aerospace Center (DLR) and industrial developments from the ArianeGroup. With a particular focus on heat transfer analyses and novel cooling concepts for thermally highly loaded structures, the book highlights the aft-body flow of the space transportation system and its interaction with the nozzle flow, which are especially critical during

the early phase of atmospheric ascent. Moreover, it describes virtual demonstrators for combustion chambers and nozzles, and discusses their industrial applicability. As such, it is a timely resource for researchers, graduate students and practitioners.

The control of vibrating systems is a significant issue in the design of aircraft, spacecraft, bridges and high-rise buildings. This 2001 book discusses the control of vibrating systems, integrating structural dynamics, vibration analysis, modern control and system identification. Integrating these subjects is an important feature in that engineers will need only one book, rather than several texts or courses, to solve vibration control problems. The book begins with a review of basic mathematics needed to understand subsequent material. Chapters then cover more recent and valuable developments in aerospace control and identification theory, including virtual passive control, observer and state-space identification, and data-based controller synthesis. Many practical issues and applications are addressed, with examples showing how various methods are applied to real systems. Some methods show the close integration of system identification and control theory from the state-space perspective, rather than from the traditional input-output model perspective of adaptive control. This text will be useful for advanced undergraduate and beginning graduate students in aerospace, mechanical and civil engineering, as well as for practising engineers. The first comprehensive reference on mechatronics, The Mechatronics Handbook was quickly embraced as the gold standard in the field. From washing machines, to coffeemakers, to cell phones, to the ubiquitous PC in almost every household, what, these days, doesn't take advantage of mechatronics in its design and function? In the scant five years since the initial publication of the handbook, the latest generation of smart products has made this even more obvious. Too much material to cover in a single volume Originally a single-volume reference, the handbook has grown along with the field. The need for easy access to new material on rapid changes in technology, especially in computers and software, has made the single volume format unwieldy. The second edition is offered as two easily digestible books, making the material not only more accessible, but also more focused. Completely revised and updated, Robert Bishop's seminal work is still the most exhaustive, state-of-the-art treatment of the field available.

Tensor Product Model Transformation in Polytopic Model-Based Control offers a new perspective of control system design. Instead of relying solely on the formulation of more effective LMIs, which is the widely adopted approach in existing LMI-related studies, this cutting-edge book calls for a systematic modification and reshaping of the polytopic convex hull to achieve enhanced performance. Varying the convexity of the resulting TP canonical form is a key new feature of the approach. The book concentrates on reducing analytical derivations in the design process, echoing the recent paradigm shift on the acceptance of numerical solution as a valid form of output to control system

problems. The salient features of the book include: Presents a new HOSVD-based canonical representation for (qLPV) models that enables trade-offs between approximation accuracy and computation complexity Supports a conceptually new control design methodology by proposing TP model transformation that offers a straightforward way of manipulating different types of convexity to appear in polytopic representation Introduces a numerical transformation that has the advantage of readily accommodating models described by non-conventional modeling and identification approaches, such as neural networks and fuzzy rules Presents a number of practical examples to demonstrate the application of the approach to generate control system design for complex (qLPV) systems and multiple control objectives. The authors' approach is based on an extended version of singular value decomposition applicable to hyperdimensional tensors. Under the approach, trade-offs between approximation accuracy and computation complexity can be performed through the singular values to be retained in the process. The use of LMIs enables the incorporation of multiple performance objectives into the control design problem and assurance of a solution via convex optimization if feasible. Tensor Product Model Transformation in Polytopic Model-Based Control includes examples and incorporates MATLAB® Toolbox TPtool. It provides a reference guide for graduate students, researchers, engineers, and practitioners who are dealing with nonlinear systems control applications.

Mechanical Vibrations: Theory and Applications takes an applications-based approach at teaching students to apply previously learned engineering principles while laying a foundation for engineering design. This text provides a brief review of the principles of dynamics so that terminology and notation are consistent and applies these principles to derive mathematical models of dynamic mechanical systems. The methods of application of these principles are consistent with popular Dynamics texts. Numerous pedagogical features have been included in the text in order to aid the student with comprehension and retention. These include the development of three benchmark problems which are revisited in each chapter, creating a coherent chain linking all chapters in the book. Also included are learning outcomes, summaries of key concepts including important equations and formulae, fully solved examples with an emphasis on real world examples, as well as an extensive exercise set including objective-type questions. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version. Advanced Applications in Acoustics, Noise and Vibration provides comprehensive and up-to-date overviews of knowledge, applications and research activities in a range of topics that are of current interest in the practice of engineering acoustics and vibration technology. The thirteen chapters are grouped into four parts: signal processing, acoustic modelling, environmental and industrial acoustics, and vibration. Following on from its companion volume Fundamentals of Noise and Vibration this book is based partly on material covered in a selection of elective modules in the second semester of

the Masters programme in 'Sound and Vibration Studies' of the Institute of Sound and Vibration Research at the University of Southampton, UK and partly on material presented in the annual ISVR short course 'Advanced Course in Acoustics, Noise and Vibration'.

This book stems from a unique and highly effective approach in introducing signal processing, instrumentation, diagnostics, filtering, control, and system integration. It presents the interactive industrial grade software testbed of mold oscillator that captures the mold motion distortion induced by coupling of the electro-hydraulic actuator nonlinearity with the resonance of the mold oscillator beam assembly. The testbed is then employed as a virtual lab to generate input-output data records that permit unraveling and refining complex behavior of the actual production system through merging dynamics, signal processing, instrumentation, and control into a coherent problem-solving package. The material is presented in a visually rich, mathematically and graphically well supported, but not analytically overburdened format. By incorporating software testbed into homework and project assignments, the book fully brings out the excitement of going through the adventure of exploring and solving a mold oscillator distortion problem, while covering the key signal processing, diagnostics, instrumentation, modeling, control, and system integration concepts. The approach presented in this book has been supported by two education advancement awards from the College of Engineering of the University of Illinois at Urbana-Champaign.

A thorough study of the oscillatory and transient motion of mechanical and structural systems, Engineering Vibrations, Second Edition presents vibrations from a unified point of view, and builds on the first edition with additional chapters and sections that contain more advanced, graduate-level topics. Using numerous examples and case studies to r

Novel mathematical and modeling approaches to problems in graded materials, biological materials, fluid mechanics and more Covers nanomechanics, multi-scale modeling, interface mechanics and microstructure This series volume contains 128 not previously published research presentations on using nonlinear mechanics to understand and model a wide variety of materials, including polymers, metals and composites, as well as subcellular and cellular tissues. Focus is on numerical and physics approaches to representing multiscale relationships within complex solids and fluids systems, with applications in materials science, energy storage, medical diagnostics and treatment, and biotechnology. TABLE OF CONTENTS Preface Committees SESSION 1: INVITED LECTURES Micro-Macro Analysis of Creep and Damage Behavior of Multi-Pass Welds Some New Developments in Non-Linear Solid Mechanics Design of Material Systems: Mathematics and Physics of the Archetype-Genome Exemplar Criticism of Generally Accepted Fundamentals and Methodologies of Traffic and Transportation Theory SESSION 2: NONLINEAR CONTINUUM MECHANICS Geometrically Nonlinear Analysis of Simple Plane Frames of Functionally Graded Materials Thermal Post-Buckling of FG Circular Plates Under Transversely Point-Space Constraint Tunability of Longitudinal Wave Band Gap in One Dimensional Magneto-Elastic Phononic Crystal Teaching Nonlinear Mechanics at the Undergraduate and Graduate Level—Two Examples Geometrically Nonlinear FE Instability Simulations of Hinged Composite Laminated Cylindrical Shells Constitutive Relation of Martensitic

Transformation in CuAlNi Based on Atomistic Simulations Soft Behaviors of Beam Shaped Liquid Crystal Elastomers Under Light Actuations XFEM Based Discontinuity Simulation for Saturated Soil Numerical Algorithm of Solving the Problem of Large Elastic-Plastic Deformation by FEM Finite Deformation for Everted Compressible Hypereleastic Cylindrical Tubes Modelling and Non-Linear Free Vibrations of Cable-Stayed Beam Wavelet Solution of a Class of Nonlinear Boundary Value Problems Axial Compression of a Rectangular Rubber Ring Composed of an Incompressible Mooney-Rivlin Material Influence of Concentration-Dependent Elastic Modulus and Charge or Discharge Rate on Tensile Stress in Anode An Integral Equation Approach to the Fully Nonlinear Fluid Flow Problem in an Infinite Channel Over Arbitrary Bottom Topography Analysis of Nonlinear Dynamical Characteristics for Thermoelastic Half-Plane with Voids Tensor Model for Dynamic Damage of Ductile Metals Over a Wide Range of Strain Rates SESSION 3: MULTI-SCALE MECHANICS AND MULTI-PHYSICS MODELING The Nonlinear Magnetoelectric Effect of Layered Magnetoelectric Composite Cylinder with an Imperfect Interface A Solution for Nonlinear Poisson-Neumann Problem of Nb3Sn Superconducting Transport Current Temperature Effect on the Tensile Mechanical Properties of Graphene Nanoribbons Square Inclusion with a Nonlinear Eigenstrain in an Anisotropic Piezoelectric Full Plane Nonlinear Analysis of the Threaded Connection with Three-Dimensional Finite Element Model Effects of Particle Volume Fraction on the Macro-Thermo-Mechanical Behaviors in Plate-Type Dispersion Nuclear Fuel Elements Mechanics of Semiflexible Polymer Chains Under Confinements Study on the Solution of Reynolds Equation for Micro Gas Bearings Using the Alternating-Direction Implication Algorithm Atomistic Study of Li Concentration Dependence of the Mechanical Properties of Graphite Anode in Li-ion Battery 3D Extrusion Simulation of the Single Screw Head and Optimization Design Buckling Behavior of Defective Carbon Nanotubes Elastic Properties of Single-Stranded DNA Biofilm with Strong Interactions Analysis on Thickness Dependence of Jc Caused by Dislocations and Grain Boundaries in YBCO Superconducting Films Operating Strain Response in CICC Coils Through Nonlinear Finite Element Modeling Dynamics Analysis of a Multi-Degree-of-Freedom Electro-Hydraulic Mix-Drive Motion Simulator by KANE Equation Multiscale 3D Fracture Simulation Integrating Tomographic Characterization Research into Compressive Mechanical Properties of Special Piezomagnetic Material Sheets A Numerical Study on Detonation Wave Propagation Using High-Precision and High-Resolution Schemes SESSION 4: STRUCTURAL DYNAMIC AND STRUCTURE-FLUID INTERACTIONS A Study on Pure IL VIV of a Marine Riser in Shear Current Parametric Studies on Nonlinear Flutter of High-Aspect-Ratio Flexible Wings Model Reduction of a Flexible Beam Rotating at High Speed Considering Dynamic Stiffening Vibration Modal Analysis of Cantilever Beams with Complicated Elasticity Boundary Constraint Numerical Simulation of Ahmed Model in Consideration of the FSI Effect Aerodynamic Damping of a Hammerhead Launch Vehicle in Transonic Flow Symmetry Reductions and Explicit Solutions of (3 + 1)-Dimensional Kadomtsev-Petviashvili (KP) Equation Nonlinear Behaviors of an Isotropic Incompressible Hyperelastic Spherical Membrane Under Different Dynamic Loads Creep Buckling of Viscoelastic Plate Consdering Higher Order Modes SESSION 5: COMPLEX FLUID FLOW AND NONLINEAR STABILITY Homotopy Analysis of Korteweg-de Vries Equation with Time Delay Homotopy Analysis

Method for Bubble Pulsation Equation with Nonlinear Term of Fractional Power Chebyshev Finite Spectral Method for Boussinesq-Type Equations on Staggered Grids Twin Jets in Crossflow Application of Fixed Point Method to Obtain a Semi-Analytical Solution of Stagnation Flow On the Nonlinear Stability of Laminar Flow Between Parallel Planes Boundary Treatments in Lattice Boltzmann Method A Lattice Boltzmann Based Immersed Boundary Method for Fluid-Structure Interaction Numerical Solutions of Convection-Diffusion Equations by Hybrid Discontinuous Galerkin Methods Steady-State Solutions of the Wave-Bottom Resonant Interaction Lattice Boltzmann Simulation of the Shock Damping and the Shock Increased by Means of Lorentz Force Analysis of the Effects of Nonlinear Characteristics of Lag Dampers on Helicopter Ground Resonance Flow Structures and Sound Radiation in Supersonic Mixing Layers with Nonlinear PSE Method Turbulent Structures in Subsonic Jet Flow Forced by Random Disturbances Exponential p-Stability for a Delayed Recurrent Neural Networks with Impulses Spatial Variation of Scaling Exponents for Structure Functions in a Decaying Turbulence SESSION 6: NONLINEAR DYNAMIC OF STRUCTURE Analysis of Chaos Behavior of Single Mode Vibration of Cable-Stayed Chaotification of Fractional Maps Nonlinear Finite Element Analysis of the Dynamic Axial Crushing of Empty Hexagonal Tube Active Control of a Nonlinear Aeroelastic System Using the Receptance Method Dynamics Analysis of the FHN Neuronal Model Analyzing the Effect of the Axial Force to the Natural Frequencies of Arch Stable Periodic Response of One-Way Clutches in a Two-Pulley Belt-Drive Model Supercritical Nonlinear Dynamics of an Axially Moving Viscoelastic Beam with Speed Fluctuation Nonlinear Dynamic Response to a Moving Force of Timoshenko Beams Resting on Pasternak Foundations An Improved Method for the Construction of Nonlinear Operator in Homotopy Analysis Method A Nonlinear Integration Scheme for Evolutionary Differential Equations A Comparative Study of Civil Aircraft Crashworthiness with Different Ground Conditions Improved Dynamic Analysis of Development of Pulmonary Edema The Timescale Function Method for Solving Free Vibration of Nonlinear Oscillator Nonlinear Aeroelastic Analysis of Flexible Wings with High-Aspect-Ratio Considering Large Deflection Differential Quadrature Method for Vibration Analysis of Finite Beams on Nonlinear Viscoelastic Foundations Numerical Simulation on the Strength and Sealing Performance for High-Pressure Isolating Flange Nonlinear Dynamical Stability of the Lattices with Initial Material and Geometric Imperfection Nonlinear Vibration of Symmetric Angle-Ply Laminated Piezoelectric Plates with Linearly Varying Thickness An Exact Free Vibration Frequency Formula for Oscillator with Single-Term Positive-Power Restoring Force An Exact Solution of Synchronization State for a Class of Networked Mass-Spring-Damper Oscillator Systems SESSION 7: INTERFACE MECHANICS AND ENGINEERING APPLICATION Numerical Simulation of Free Surface Collapse in Propellant Tank Restudy on the Adaptive Mesh Technique for Seepage Problems High-Order Series Solutions of Wave and Current Interactions Deformation and Stress Distribution of Arterial Walls of the Aged A p53-Mdm2 Dynamical Model Induced by Laminar Shear Stress in Endothelial Cells Optimized Image Processing Based on CUDA in a Combined Measurement Technique of PIV and Shadowgraph 3D Visualization of the Flow Fields Using Digital In-Line Holography Analysis and Experimental Study on Air Foam Flooding Seepage Flow Mechanics Experimental Measurements for Mechanical and Electrical Conductive Properties of CNT Bundles Analysis on Dynamic Response of Bedding Rock Slope with

Bolts under Earthquakes Numerical Prediction of Aerodynamic Noise Radiated from High Speed Train Pantograph Effects of Length on Aerodynamics of High Speed Train Models Free Convection Nanofluid Flow in the Stagnation-Point Region of a Three Dimensional Body Vertical Distribution and Dynamic Release Characteristics of Pollutants from Resuspended Sediment Numerical Simulation of the Contaminant Release Through the Sediment-Overlying Water Interface Analysis on the Aerodynamic and Aero-Noise of MIRA Model Radial Squeeze Force of MR Fluid Between Two Cylinders Nonlinear Buckling Analysis and Ultimate Extended Capacity Research of Downhole Pipe Strings in Ultra-Deep Horizontal Wells A Novel Method of Generating Nonlinear Internal Wave in a Stratified Fluid Tank and Its Theoretical Model SESSION 8: MINI-SYMPOSIUM ON TRAFFIC FLUID Study on Correlation Analysis of Synchronized Flow in the Kerner-Klenov-Wolf Cellular Automation Model Numerical Simulation of Traffic Flow in the Rain or Snow Weather Condition First Order Phase Transitions in the Brake Light Cellular Automation Model Within the Fundamental Diagram Approach The Leader-Follower Winding Behavior of Pedestrians in a Queue Effect of Overpasses in Two-Dimensional Traffic Flow Model with Random Update Rule Analysis of the Density Wave in a New Continuum Model The Phenomenon of High-Speed-Car-Following on Chinese Highways A Lattice Hydrodynamic Model Considering the Difference of Density and its Analysis Experimental Feature of Car-Following Behaviors in a Platoon of 25 Vehicles Car-Following Model for Manual Transmission Vehicles The Mechanism of Synchronized Flow in Traffic Flow Modeling An Asymmetric Stochastic Car-Following Model Based on Extended Tau Theory A Gaussian Distribution Based Dual-Cognition Driver Behavior Model at Cross Traffic A New Traffic Kinetic Model Considering Potential Influence The Effect of Marks on the Pedestrian Evacuation Equilibrium Velocity Distribution Function for Traffic Flow Effects of Antilock Braking System on Driving Behavior Under Emergent Stability Analysis of Pedestrian Flow in Two-Dimensional Optimal Velocity Model with Asymmetric Interaction Simulation-Based Stability Analysis of Car-Following Models Under Heterogeneous Traffic Crossing Speed of Pedestrian at an Unsignalized Intersection Modeling Mixed Traffic Flow at a Crosswalk with Push Button Effects of Game Strategy Update on Pedestrian Evacuation in a Hall Study on Long-Term Correlation of CO and CO_2 from Vehicle Emissions on Roadsides with the Detrended Fluctuation Analysis Method Bottleneck Effect on a Bidirectional Two-Lane Mixed Traffic Flow

An in-depth introduction to the foundations of vibrations for students of mechanical engineering For students pursuing their education in Mechanical Engineering, An Introduction to Mechanical Vibrations is a definitive resource. The text extensively covers foundational knowledge in the field and uses it to lead up to and include: finite elements, the inerter, Discrete Fourier Transforms, flow-induced vibrations, and self-excited oscillations in rail vehicles. The text aims to accomplish two things in a single, introductory, semester-length, course in vibrations. The primary goal is to present the basics of vibrations in a manner that promotes understanding and interest while building a foundation of knowledge in the field. The secondary goal is to give students a good understanding of two topics that are ubiquitous in today's engineering workplace - finite element analysis (FEA) and Discrete Fourier Transforms (the DFT- most often seen in the form of the Fast Fourier Transform or FFT). FEA and FFT software tools are readily available to both students and practicing engineers and they need to be used

with understanding and a degree of caution. While these two subjects fit nicely into vibrations, this book presents them in a way that emphasizes understanding of the underlying principles so that students are aware of both the power and the limitations of the methods. In addition to covering all the topics that make up an introductory knowledge of vibrations, the book includes: ? End of chapter exercises to help students review key topics and definitions ? Access to sample data files, software, and animations via a dedicated website

This volume encompasses prototypical, innovative and emerging examples and benchmarks of Differential-Algebraic Equations (DAEs) and their applications, such as electrical networks, chemical reactors, multibody systems, and multiphysics models, to name but a few. Each article begins with an exposition of modelling, explaining whether the model is prototypical and for which applications it is used. This is followed by a mathematical analysis, and if appropriate, a discussion of the numerical aspects including simulation. Additionally, benchmark examples are included throughout the text. Mathematicians, engineers, and other scientists, working in both academia and industry either on differential-algebraic equations and systems or on problems where the tools and insight provided by differential-algebraic equations could be useful, would find this book resourceful.