

Bond Graph In Modeling Simulation And Fault Identification 2nd Edition

In spite of the energy crisis, population and environment degradation issues, the use of automobiles has been going up. This call for continuing the efforts towards developing more efficient, environmentally friendly, safer and more controllable vehicles. This often translates into developing better models and increasing the use of onboard computers. The use of computers for control invariably requires models which execute faster and are reliable even in extreme conditions. Bond graph based techniques allow the development of continuously extensible models and easier integration with control systems. The present work deals with the development of the so called half car models using Bond graph based approaches to study the response of the vehicle while passing over a ramp or uneven surface. A successful compilation of the Bond graph on the Bond graph package Symbol Shakti shows that the model has been created with logical correctness. More extensive validation may be needed before it can be taken up for testing its utility for online control.

This book provides control engineers and workers in industrial and academic research establishments interested in process engineering with a means to build up a practical and functional supervisory control environment and to use sophisticated models to get the best use out of their process data. Several applications to academic and small-scale industrial processes are discussed and the development of a supervision platform for an industrial plant is presented.

Nowadays, engineering systems are of ever-increasing complexity and must be considered as multidisciplinary systems composed of interacting subsystems or system components from different engineering disciplines. Thus, an integration of various engineering disciplines, e.g. mechanical, electrical and control engineering in a current design approach is required. With regard to the systematic development and analysis of system models, interdisciplinary computer aided methodologies are coming more and more important. A graphical description formalism particularly suited for multidisciplinary systems are bond graphs devised by Professor Henry Paynter in as early as 1959 at the Massachusetts Institute of Technology (MIT) in Cambridge, Massachusetts, USA and in use since then all over the world. This monograph is devoted exclusively to the bond graph methodology. It gives a comprehensive, in-depth, state-of-the-art presentation including recent results scattered over research articles and dissertations and research contributions by the author to a number of topics. The book systematically covers the fundamentals of developing bond graphs and deriving mathematical models from them, the recent developments in methodology, symbolic and numerical processing of mathematical models derived from bond graphs. Additionally it discusses modern modelling languages, the paradigm of object-oriented modelling, modern software that can be used for building and for processing of bond graph models, and provides a chapter with small case studies illustrating various applications of the methodology.

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Este trabalho tem por objetivo a modelagem do comportamento dinâmico do motor de CC shunt, através da metodologia dos grafos de ligação. Primeiro será feito um levantamento de todos os parâmetros mecânicos, elétricos e magnéticos da máquina. O segundo passo será a obtenção de um grafo de ligação do motor e de suas respectivas equações de estado representativas. Através destas equações e dos parâmetros obtidos em laboratório será montado um modelo de simulação computacional pelo Matlab para verificação do comportamento da máquina desde a partida até o regime permanente, comprovando a veracidade do modelo.

This book provides an open platform to establish and share knowledge developed by scholars, scientists, and engineers from all over the world, about various applications of the modeling and simulation in the design process of products, in various engineering fields. The book consists of 12 chapters arranged in two sections (3D Modeling and Virtual Prototyping), reflecting the multidimensionality of applications related to modeling and simulation. Some of the most recent modeling and simulation techniques, as well as some of the most accurate and sophisticated software in treating complex systems, are applied. All the original contributions in this book are jointed by the basic principle of a successful modeling and simulation process: as complex as necessary, and as simple as possible. The idea is to manipulate the simplifying assumptions in a way that reduces the complexity of the model (in order to make a real-time simulation), but without altering the precision of the results.

Recently there has been considerable interest in qualitative methods in simulation and mathematical modeling. Qualitative Simulation Modeling and Analysis is the first book to thoroughly review fundamental concepts in the field of qualitative simulation. The book will appeal to readers in a variety of disciplines including researchers in simulation methodology, artificial intelligence and engineering. This book boldly attempts to bring together, for the first time, the qualitative techniques previously found only in hard-to-find journals dedicated to single disciplines. The book is written for scientists and engineers interested in improving their knowledge of simulation modeling. The "qualitative" nature of the book stresses concepts of invariance, uncertainty and graph-theoretic bases for modeling and analysis.

The main object of this advanced textbook is modelling and simulation of energetic processes by bond graphs. But even without knowledge of this powerful method, it can be used to a certain extent as an introduction to simulation in thermodynamics.

System Dynamics is a cornerstone resource for engineers faced with the evermore-complex job of designing mechatronic systems involving any number of electrical, mechanical, hydraulic, pneumatic, thermal, and magnetic subsystems. This updated Fourth Edition offers the latest coverage on one of the most important design tools today—bond graph modeling—the powerful, unified graphic modeling language. The only comprehensive guide to modeling, designing, simulating, and analyzing dynamic systems comprising a variety of technologies and energy domains, System Dynamics, Fourth Edition continues the previous edition's step-by-step approach to creating dynamic models. (Midwest). This book presents bond graph model-based fault detection with a focus on hybrid system models. The book addresses model design, simulation, control and model-based fault diagnosis of multidisciplinary engineering systems. The text begins with a brief survey of the state-of-the-art, then focuses on hybrid systems. The author then uses different bond graph approaches throughout the text and provides case studies.

This book introduces modeling and simulation of linear time invariant systems and demonstrates how these translate to systems engineering, mechatronics engineering, and biomedical engineering. It is organized into nine chapters that follow the lectures used for a one-semester course on this topic, making it appropriate for students as well as researchers. The author discusses state space modeling derived from two modeling techniques and the analysis of the system and usage of modeling in control systems design. It also contains a unique chapter on multidisciplinary energy systems with a special focus on bioengineering systems and expands upon how the bond graph augments research in biomedical and bio-mechatronics systems.

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Modeling and simulation form an integral role in the engineering design process. An accurate mathematical description of a system provides the design engineer the flexibility to perform trade studies quickly and accurately to expedite the design process. Most often, the mathematical model of the system contains components of different engineering disciplines. A modeling methodology that can handle these types of systems might be used in an indirect fashion to extract added information from the model. This research examines the ability of a modeling methodology to provide added insight into system analysis and design. The modeling methodology used is bond graph modeling. An investigation into the creation of a bond graph model using the Lagrangian of the system is provided. Upon creation of the bond graph, system analysis is performed. To aid in the system analysis, an object-oriented approach to bond graph modeling is introduced. A framework is provided to simulate the bond graph

directly. Through object-oriented simulation of a bond graph, the information contained within the bond graph can be exploited to create a measurement of system efficiency. A definition of system efficiency is given. This measurement of efficiency is used in the design of different controllers of varying architectures. Optimal control of a missile autopilot is discussed within the framework of the calculated system efficiency.

Bondgraphs are a well-established technique for the modelling of complex engineering systems. The subject of this book is an integrated modelling and simulation of mechatronics systems in a visual computer environment. The modelling is based on system top-down and bottom-up approach. The mathematical models are generated in a form of differential-algebraic equations and solved using numerical and symbolic algebra methods. The integrated approach developed is applied to mechanical, electrical and control systems, multibody dynamics, and continuous systems. The book contains a powerful computer simulation package on the accompanying CD-ROM.

One of the most significant challenges in the development of embedded and cyber-physical systems is the gap between the disciplines of software and control engineering. In a marketplace, where rapid innovation is essential, engineers from both disciplines need to be able to explore system designs collaboratively, allocating responsibilities to software and physical elements, and analyzing trade-offs between them. To this end, this book presents a framework that allows the very different kinds of design models – discrete-event (DE) models of software and continuous time (CT) models of the physical environment – to be analyzed and simulated jointly, based on common scenarios. The individual chapters provide introductions to both sides of this co-simulation technology, and give a step-by-step guide to the methodology for designing and analyzing co-models. They are grouped into three parts: Part I introduces the technical basis for collaborative modeling and simulation with the Crescendo technology. Part II continues with different methodological guidelines for creating co-models and analyzing them in different ways using case studies. Part III then delves into more advanced topics and looks into the potential future of this technology in the area of cyber-physical systems. Finally various appendices provide summaries of the VDM and 20-sim technologies, a number of valuable design patterns applicable for co-models, and an acronym list along with indices and references to other literature. By combining descriptions of the underlying theory with records of real engineers' experience in using the framework on a series of case studies the book appeals to scientists and practitioners alike. It is complemented by tools, examples, videos, and other material on www.crescendotool.org. Scientists/researchers and graduate students working in embedded and cyber-physical systems will learn the semantic foundations for collaborative modeling and simulation, as well as the current capabilities and limitations of methods and tools in this field. Practitioners will be able to develop an appreciation of the capabilities of the co-modeling techniques, to assess the benefits of more collaborative approaches to modeling and simulation, and will benefit from the included guidelines and modeling patterns.

Abstract: Electric bicycles are widely available in user markets. However their use as a daily commuting vehicle is limited due to the need for frequent recharging. This thesis focuses on the mathematical modeling of electrical bicycle with regenerative braking. Basic bond graphs methods are discussed here to develop state space models for mechatronic systems. A bond graph based mathematical model of an electric bicycle with regeneration is developed in this thesis. Mathematical models are tested in simulation, generating different road scenarios. Parameters required for the simulation are calculated using an experimental setup. The thesis shows the capability of bond graphs to assist in calculations for regenerative charging. The main focus of this thesis is to evaluate simulation models against a prototype. Simulation results and road testing of the prototype indicate the regenerative braking is not only feasible, but an advantage to implement in an electric bicycle. It is shown that the distance between battery recharge is improved by as much as 10% depending on riding conditions.

Bond graphs are especially well-suited for mechatronic systems, as engineering system modeling is best handled using a multidisciplinary approach. Bond graphing permits one to see the separate components of an engineering system as a unified whole, and allows these components to be categorized under a few generalized elements, even when they come from different disciplines. In addition to those advantages, the bond graph offers a visual representation of a system from which derivation of the governing equations is algorithmic. This makes the design process accessible to beginning readers, providing them with a practical understanding of mechatronic systems. *Mechatronic Modeling and Simulation Using Bond Graphs* is written for those who have some hands-on experience with mechatronic systems, enough to appreciate the value of computer modeling and simulation. Avoiding elaborate mathematical derivations and proofs, the book is written for modelers seeking practical results in addition to theoretical confirmations. Key concepts are revealed step-by-step, supported by the application of rudimentary examples that allow readers to develop confidence in their approach right from the start. For those who take the effort to master its application, the use of bond graph methodology in system modeling can be very satisfying in the way it unifies information garnered from different disciplines. In the second half of the book after readers have learned how to develop bond graph models, the author provides simulation results for engineering examples that encourage readers to model, simulate, and practice as they progress through the chapters. Although the models can be simulated using any number of software tools, the text employs 20Sim for all the simulation work in this text. A free version of the software can be downloaded from the 20Sim Web site.

This book shows in a comprehensive presentation how Bond Graph methodology can support model-based control, model-based fault diagnosis, fault accommodation, and failure prognosis by reviewing the state-of-the-art, presenting a hybrid integrated approach to Bond Graph model-based fault diagnosis and failure prognosis, and by providing a review of software that can be used for these tasks. The structured text illustrates on numerous small examples how the computational structure superimposed on an acausal bond graph can be exploited to check for control properties such as structural observability and control lability, perform parameter estimation and fault detection and isolation, provide discrete values of an unknown degradation trend at sample points, and develop an inverse model for fault accommodation. The comprehensive presentation also covers failure prognosis based on continuous state estimation by means of filters or time series forecasting. This book has been written for students specializing in the overlap of engineering and computer science as well as for researchers, and for engineers in industry working with modelling,

simulation, control, fault diagnosis, and failure prognosis in various application fields and who might be interested to see how bond graph modelling can support their work. Presents a hybrid model-based, data-driven approach to failure prognosis Highlights synergies and relations between fault diagnosis and failure prognostic Discusses the importance of fault diagnosis and failure prognostic in various fields

This book presents theory and latest application work in Bond Graph methodology with a focus on: • Hybrid dynamical system models, • Model-based fault diagnosis, model-based fault tolerant control, fault prognosis • and also addresses • Open thermodynamic systems with compressible fluid flow, • Distributed parameter models of mechanical subsystems. In addition, the book covers various applications of current interest ranging from motorised wheelchairs, in-vivo surgery robots, walking machines to wind-turbines. The up-to-date presentation has been made possible by experts who are active members of the worldwide bond graph modelling community. This book is the completely revised 2nd edition of the 2011 Springer compilation text titled Bond Graph Modelling of Engineering Systems – Theory, Applications and Software Support. It extends the presentation of theory and applications of graph methodology by new developments and latest research results. Like the first edition, this book addresses readers in academia as well as practitioners in industry and invites experts in related fields to consider the potential and the state-of-the-art of bond graph modelling.

Bond graphs have become a part of undergraduate and postgraduate curricula at technological and engineering institutes. Many industries, organizations, universities, and academic institutions have included bond graphs in their research, development, and design activities. In recent years, the range of applications of bond graphs has enhanced owing to sustained research in this field. Bond Graph in Modeling, Simulation and Fault Identification is an outcome of the authors' teaching System-modeling, Dynamics and Control through bond graphs for the last 15 years. It is organized into 16 chapters and is narrative in style to make it easily comprehensible to students. Each chapter is appended with a set of problems divided into two groups: problems to be solved by students for usual practice and project-type problems.

The author presents current work in bond graph methodology by providing a compilation of contributions from experts across the world that covers theoretical topics, applications in various areas as well as software for bond graph modeling. It addresses readers in academia and in industry concerned with the analysis of multidisciplinary engineering systems or control system design who are interested to see how latest developments in bond graph methodology with regard to theory and applications can serve their needs in their engineering fields. This presentation of advanced work in bond graph modeling presents the leading edge of research in this field. It is hoped that it stimulates new ideas with regard to further progress in theory and in applications.

The standard in the field, updated and revised for today's complex mechatronic systems More than ever before, engineers are responsible for the total system design of the products they create. While traditional modeling and simulation methods are useful in the design of static components, they are of little assistance to those charged with designing mechatronic systems comprising a variety of technologies and energy domains. Engineers who design such complex systems need more sophisticated tools to help them think and visualize on a dynamic systems level. This book arms them with one of the most important of those tools-bond graph modeling, a powerful unified graphic modeling language. System Dynamics, Third Edition is the only comprehensive guide to modeling, designing, simulating, and analyzing dynamic systems comprising any number of electrical, mechanical, hydraulic, pneumatic, thermal, and magnetic subsystems. While it has been updated and expanded to include many new illustrations, expanded coverage of computer simulation models, and more detailed information on dynamic system analysis, it has lost none of the qualities that have helped make it the standard text/reference in the field worldwide. With the help of more than 400 illustrations, the authors demonstrate step by step how to: * Model a wide range of mechatronic systems using bond graphs * Experiment with subsystem models to verify or disprove modeling decisions * Extract system characteristics and predict system behaviors * Translate graphical models into complex mathematical simulations * Combine bond graph modeling with state-of-the-art software simulation tools System Dynamics, Third Edition is an indispensable resource for practicing engineers as well as students of mechanical, electrical, aeronautical, and chemical engineering.

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